

## ASSESSMENT OF AMPLITUDE FACTORS OF ASYMPTOTIC EXPANSION AT CRACK TIP IN FLEXOELECTRIC SOLID UNDER MODE I LOADINGS

Profant T.<sup>\*</sup>, Sládek J.<sup>\*\*</sup>, Sládek V.<sup>\*\*\*</sup>, Kotoul M.<sup>†</sup>

**Abstract:** *The flexoelectric effect is the consequence of the coupling of the large strain gradients and the electric polarization in dielectric materials. The large strain gradients appear near the material defects, especially at the crack tips, where the flexoelectric effect redistributes the stress field and influences the crack behaviour and formation. The flexoelectricity is the size dependent material property, which must be included in the governing equilibrium equations. The consequence of this fact is the more complicated form of the asymptotic solution at the crack tip than the asymptotic solution in the classical elasticity. The asymptotic solution at the crack tip in flexoelectric material contains four amplitude factors in the case of the mode I loading conditions. It is purpose of this contribution to derive the expressions of these amplitude factors as the functions of the stress intensity factor  $K_I$ . The matched asymptotic expansions method is used to assess the amplitude factors. The crack process zone characterized by the size material parameter  $l$  is chosen as the boundary layer.*

**Keywords:** Crack, Flexoelectricity, Matched asymptotic expansions, Amplitude factors, Asymptotic solution.

### 1. Introduction

The flexoelectric effect is the size dependent material property existing in all dielectric materials, see (Yudin, 2013) or (Zubko, 2013). The coupling of the large strain gradients and the electric polarization causes this effect near the material defects and consequently influences the distribution and evolution of the stress fields. The large strain gradients usually occur near the crack tip and therefore it is relevant to suppose that the crack formation and propagation are affected by the flexoelectricity in the dielectric materials, (Tian, 2022). An interesting finding in orthopedics is the self-repairing and remodeling mechanism of micro-cracks in human bones based on the flexoelectric effect, (Vasquez-Sancho, 2018) and (Nunez-Toldra, 2020). Despite many experimental studies of the flexoelectric effect near the crack tip, the detailed theoretical investigation of fracture process in flexoelectric solids is still missing. The reason for this research imbalance is the difficulty in the obtaining of the adequate solution of the partial differential equations of the fourth order which describe the equilibrium of the flexoelectric body. It is extremely difficult or impossible to find the analytical as well as numerical solution of the fracture problem in the solids with the size dependent and flexoelectric material properties. All these solutions are obtained under the simplified or weakened conditions, (Shu, 1999; Grenzou, 2008; Tian, 2021) and (Repka, 2018). The strain gradient theory for elastic dielectrics was pioneered by Toupin (1962), the first continuum mechanics theory for flexoelectric solids was proposed by Mindlin (1968). The analytical solution shows that the singularity of stresses accounting the strain gradient effect near the crack tip is  $p = -3/2$ . This singularity is significantly stronger than their counterparts in the classical fracture mechanics. On the other hand, there is no singularity of Cauchy stresses at the crack tip in the strain gradient elastic theory. It is proportional to

<sup>\*</sup> Doc. Ing. Tomáš Profant, PhD.: Institute of Solid Mechanics, Mechatronics and Biomechanics, Faculty of Mechanical Engineering, BUT, Technická 2896/2, Brno, 616 69, Czech Republic, profant@fme.vutbr.cz

<sup>\*\*</sup> Prof. Ing. Ján Sládek, DrSc.: Department of Mechanics, Slovak Academy of Sciences, Bratislava 984503, Slovak Republic, jan.sladek@savba.sk

<sup>\*\*\*</sup> Prof. RNDr. Vladimír Sládek, DrSc.: Department of Mechanics, Slovak Academy of Sciences, Bratislava 984503, Slovak Republic, vladimir.sladek@savba.sk

<sup>†</sup> Prof. RNDr. Michal Kotoul, DrSc.: Institute of Solid Mechanics, Mechatronics and Biomechanics, Faculty of Mechanical Engineering, BUT, Technická 2896/2, Brno, 616 69, Czech Republic, kotoul@fme.vutbr.cz

$p = 1/2$  and its structure is different from the classical stress field controlled by the stress intensity factor  $K$ , (Kotoul, 2018; Tian, 2022). Based on the Toupin–Mindlin generalized continuum theory of dipolar gradient elasticity, (Georgiadis, 2003) and (Gourgiotis, 2009) derived the expressions for stress and displacement field at the crack tip in a micro-structured solid under remotely loading (plane strain loading for Mode I and II cracks, anti-plane shear loading for Mode III crack). It is noteworthy that the definition of the J-integral with strain gradient effects is also extended by Georgiadis (2003). Aravas (2009) also developed an asymptotic crack tip solution for a material that obeyed a special form of linear isotropic strain gradient elasticity. Mao (2015) performed an asymptotic analysis of the crack tip field in the flexoelectric solids, which is applied in the analysis discussed in this contribution.

## 2. Governing equations

It is considered an isotropic dielectric solid  $\Omega$  with flexoelectricity, whose energy density function  $U(\boldsymbol{\varepsilon}, \nabla \boldsymbol{\varepsilon}, \mathbf{P})$  depends on the infinitesimal strain tensor  $\boldsymbol{\varepsilon}$ , its gradient  $\nabla \boldsymbol{\varepsilon}$  and the polarization vector field  $\mathbf{P}$ . The Cauchy stress  $\boldsymbol{\sigma}$  and the dipolar stress  $\boldsymbol{\tau}$  can be defined in variational manner

$$\sigma_{ij} = \frac{\partial U}{\partial \varepsilon_{ij}}, \quad \tau_{ijk} = \frac{\partial U}{\partial (\partial_i \varepsilon_{jk})} \quad (1)$$

and must satisfy the governing equilibrium equations, Mao (2015),

$$\nabla \cdot (\boldsymbol{\sigma} - \nabla \cdot \boldsymbol{\tau}) = 0, \quad (2)$$

$$-\epsilon_0 \nabla^2 \varphi + \nabla \cdot \mathbf{P} = 0, \quad (3)$$

$$\mathbf{E} + \nabla \varphi = 0, \quad (4)$$

where the body force per volume is omitted,  $\epsilon_0$  is permittivity of vacuum,  $\mathbf{E}$  is electric field and  $\varphi$  is electric potential. The isotropic flexoelectric solid is characterized by the Lamé coefficients  $\lambda$  and  $\mu$ , the Poisson ratio  $\nu$ , the length scale parameter  $l$ , two flexoelectric constants  $f_1$  and  $f_2$ , the dielectric permittivity  $\epsilon$  and by the dependency of the polarization vector field  $\mathbf{P}$  on the strain gradients  $\nabla \boldsymbol{\varepsilon}$ . Consequently, the constitutive equations are given as

$$\boldsymbol{\sigma} = \lambda \text{Tr}(\boldsymbol{\varepsilon}) \mathbf{I} + 2\mu \boldsymbol{\varepsilon}, \quad (5)$$

$$\mathbf{P} = a^{-1} [\mathbf{E} - f_1 \nabla \text{Tr}(\boldsymbol{\varepsilon}) - 2f_2 \nabla \cdot \boldsymbol{\varepsilon}], \quad (6)$$

$$\boldsymbol{\tau} = l^2 \nabla \boldsymbol{\sigma} + f_1 (\mathbf{P} \mathbf{e}_i \mathbf{e}_j + \mathbf{P} \mathbf{e}_j \mathbf{e}_i) + f_2 (\mathbf{e}_i \mathbf{e}_i \mathbf{P} + \mathbf{e}_j \mathbf{e}_j \mathbf{P}) + f_2 (\mathbf{e}_i \mathbf{P} \mathbf{e}_i + \mathbf{e}_j \mathbf{P} \mathbf{e}_j), \quad (7)$$

The basis vectors  $\mathbf{e}_i$  and  $\mathbf{e}_j$  represent the basis of Cartesian or polar coordinate system and  $a$  is reciprocal susceptibility constant given by the relation

$$a^{-1} = \epsilon - \epsilon_0, \quad (8)$$

The governing equations admit following natural boundary conditions

$$\mathbf{n} \cdot (\boldsymbol{\sigma} - \nabla \cdot \boldsymbol{\tau}) - \tilde{\nabla} \cdot (\mathbf{n} \cdot \boldsymbol{\tau}) + (\tilde{\nabla} \cdot \mathbf{n}) \mathbf{n} \cdot (\mathbf{n} \cdot \boldsymbol{\tau}) = \mathbf{t} \text{ on } \partial \Omega_t, \quad (9)$$

$$\mathbf{n} \cdot (\mathbf{n} \cdot \boldsymbol{\tau}) = \mathbf{r} \text{ on } \partial \Omega_r, \quad (10)$$

$$\mathbf{n} \cdot (\epsilon_0 \mathbf{E} + \mathbf{P}) = \omega \text{ on } \partial \Omega_D, \quad (11)$$

where  $\mathbf{t}$  is the auxiliary force traction,  $\mathbf{r}$  is the double force traction,  $\omega$  is surface charge,  $\mathbf{n}$  is the external normal to the boundary  $\partial \Omega$  and  $\tilde{\nabla} = (\mathbf{I} - \mathbf{n} \mathbf{n}) \cdot \nabla$ . It is also practical to introduce non-dimensional parameters

$$\alpha = \frac{f_2}{l\sqrt{a\mu}}, \quad \beta = \frac{f_1 + 2f_2}{l\sqrt{a\mu}} \quad (12)$$

## 3. Matched asymptotic expansions

The following fracture problem assumes the existence of the crack of the length  $2L$  in the dielectric material which is under the mode I mechanical loading conditions. The so-called outer solution is the singular asymptotic solution of this problem at the crack tips characterized by the stress intensity factor  $K_I$ . There

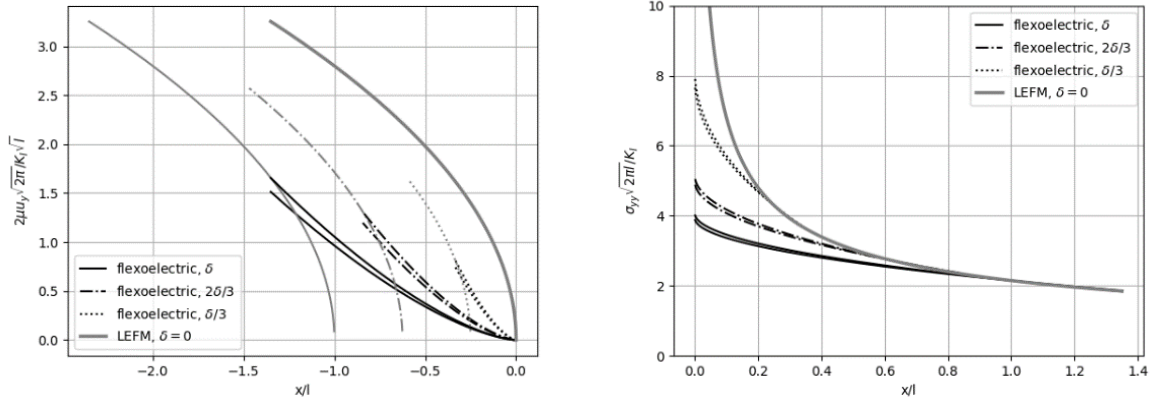


Fig. 1: The crack tip opening displacements  $u_y$  (left) and the stress  $\sigma_{yy}$  in front of the crack tip (right) for LELM and flexoelectric material.

are also domains with characteristic dimensions  $l \ll L$  at the crack tips, where the strain gradients prevail and couple with electric polarization. The flexoelectric effect must be considered in these small domains, where the dielectric continuum is governed by the equilibrium equations (2)-(4) and the following boundary conditions along the crack faces

$$\mathbf{t}(r, \theta) = \mathbf{r}(r, \theta) = \omega(0, \theta) = 0 \text{ for } \theta = \pm\pi, \quad (13)$$

where  $(r, \theta)$  is the polar coordinate system introduced at the crack tip. The boundary conditions (13) and equilibrium equations (2)-(4) allow one to derive the so-called inner asymptotic solution for the Cauchy stress  $\boldsymbol{\sigma}$  whose radial and tangential components are as follows

$$\sigma_{rr}^{in} = 2\Gamma_1(\lambda + \mu) + 2\Gamma_2 \cos 2\theta + 2\Gamma_3 \mu \sin 2\theta + \delta^{1/2} R^{1/2} \left\{ \left[ A_1 \left( \frac{5}{2} \lambda + 3\mu \right) + A_4 \frac{1}{2} \lambda \right] \cos \frac{1}{2} \theta + A_3 \left[ \frac{1}{2} \lambda (3l_{12} + 5) + 3\mu \right] \cos \frac{3}{2} \theta + 3A_2 \mu \cos \frac{5}{2} \theta \right\}, \quad (14)$$

$$\sigma_{r\theta}^{in} = 2\mu(-\Gamma_2 \sin 2\theta + \Gamma_3 \cos 2\theta) + \delta^{1/2} R^{1/2} \left\{ \frac{1}{2} \mu(-A_1 + A_4) \sin \frac{1}{2} \theta - 3A_2 \mu \sin \frac{5}{2} \theta - \frac{1}{2} A_3 \mu (-l_{12} + 3) \sin \frac{3}{2} \theta \right\}, \quad (15)$$

where  $l_{12}$  is non-dimensional parameter depending on flexoelectric constants. The inner domain represents the crack process zone  $r \ll l$ , in which the flexoelectric effects are appeared due to the dominance of the strain gradients. The inner domain can be characterized by the non-dimensional parameter  $\delta = l/L \ll 1$  and the scaled coordinate system  $(R, \theta) \equiv (r\delta^{-1}, \theta)$  allowing the evaluation of the amplitude factors  $A_1$ - $A_4$  as the functions of the stress intensity factor  $K_I$ . The strain gradients and dipolar stress  $\boldsymbol{\tau}$  decrease to zero value with the increasing distance  $r$  from the crack tip. Consequently, the auxiliary force traction (9) converges to the standard traction vector  $\mathbf{t} = \mathbf{n} \cdot \boldsymbol{\sigma}$ . The double force tractions (10) and surface charge (11) disappear. Hence in the case of the circular shaped remote boundary of the outer domain ( $R \rightarrow l\delta^{-1} = L$ ) as well as the near crack tip boundary of the inner domain ( $r \rightarrow l$ ), the following equalities can be considered

$$\mathbf{t}^{out}|_{r=l} \approx \mathbf{t}^{in}|_{R=l\delta^{-1}=L} \Rightarrow \sigma_{rr}^{out}|_{r=l} \approx -\sigma_{rr}^{in}|_{R=l\delta^{-1}=L}, \sigma_{r\theta}^{out}|_{r=l} \approx -\sigma_{r\theta}^{in}|_{R=l\delta^{-1}=L}. \quad (16)$$

The substitution (14) and (15) into (16) leads to the overdetermined system of algebraic equations with unknowns  $A_1$ - $A_4$ . This system gives unique solution for  $A_1$ ,  $A_3$  and  $A_4$ . The magnitude of amplitude factor  $A_2$  oscillates between two opposite values

$$A_1 = -\frac{K_I}{(2\pi)^{1/2}} \frac{\lambda - 5\mu}{12l\mu(\lambda + \mu)}, A_2 = \pm \frac{K_I}{(2\pi)^{1/2}} \frac{l_{12}(3\lambda + \mu) + 5\lambda + 3\mu}{12l\mu[l_{12}(3\lambda - \mu) + 5\lambda + 9\mu]}, \quad (17)$$

$$A_3 = -\frac{K_I}{(2\pi)^{1/2}} \frac{1}{l[l_{12}(3\lambda - \mu) + 5\lambda + 9\mu]}, A_4 = \frac{K_I}{(2\pi)^{1/2}} \frac{5\lambda + 11\mu}{12\mu l(\lambda + \mu)} \quad (18)$$

The parameters  $\Gamma_1$ ,  $\Gamma_2$  and  $\Gamma_3$  depends on the finite values of the Cauchy stress  $\boldsymbol{\sigma}$  at the crack tips. These values are unavailable and must be assessed from the values of  $\boldsymbol{\sigma}^{out}$  near the crack tip, e.g. in the distance  $r = l$  and  $\theta = 0$ .

#### 4. Numerical results

It is considered the dielectric material with  $\alpha = -0.572$  and  $\beta = -0.499$ . Figure 1 shows the crack opening displacements  $u_y$  and the Cauchy stress  $\sigma_{yy}$  in front of crack tip for varying parameter  $\delta$ ,  $2\delta/3$  and  $\delta/3$ , where  $\delta = 1 \times 10^{-3}$ . The dark lines represent the inner solutions which consider the flexoelectric effect in the crack process zone with dimension  $l$ . The top and bottom line of each inner solution correspond to  $\pm A_2$ , respectively. The minimal influence of the amplitude factor  $A_2$  on the stress and displacement field at the crack tip is obvious. The gray lines represent outer solutions corresponding to the negligible influence of strain gradients and consequently no flexoelectric effects. The LEFM solution for  $\delta = 0$  is also depicted as the grey thick line. It can be seen good transition between the outer and the inner solution inside the boundary layers  $x/l \sim 1, 2/3$  and  $1/3$ .

#### 5. Conclusions

The contribution discussed the procedure of the assessment of the amplitude factors appearing in the asymptotic solution of the crack in the flexoelectric solid. The amplitude factors are evaluated under the assumption of the knowledge of the stress intensity factor  $K_I$  representing the classical solution of LEFM. There are many ways to redistribute  $K_I$  among four amplitude factors appearing in the asymptotic flexoelectric solution and the used matched asymptotic expansion method seems to be applicable tool to get the relevant result

#### Acknowledgement

The authors acknowledge the supports by the Slovak Science and Technology Assistance Agency registered under number APVV-18-0004, VEGA-2/0061/20.

#### References

- Aravas, N. and Giannakopoulos, A. E. (2009) Plane asymptotic crack-tip solutions in gradient elasticity. *Int. J. Solids. Struct.*, 46, 25-26, pp. 4478–4503.
- Georgiadis, H. G. (2003) The Mode III Crack Problem in Microstructured Solids Governed by Dipolar Gradient Elasticity: Static and Dynamic Analysis. *ASME. J. Appl. Mech.*, 70, 4, pp. 517-530.
- Gourgiotis, P. A. and Georgiadis, H. G. (2009) Plane-strain crack problems in microstructured solids governed by dipolar gradient elasticity. *J. Mech. Phys. Solids.*, 57, 11, pp. 1898–1920.
- Grenzelou, C.G. and Georgiadis, H.G. (2008) Balance laws and energy release rates for cracks in dipolar gradient elasticity. *International Journal of Solids and Structures*, 45, pp. 551-567.
- Kotoul, M. and Profant, T. (2018) Asymptotic solution for interface crack between two materials governed by dipolar gradient elasticity. *Engineering Fracture Mechanics*, 201, pp. 80-106.
- Mao, S. and Purohit, P. K. (2015) Defects in flexoelectric solids. *J. Mech. Phys. Solids.*, 84, pp. 95-115.
- Mindlin, R. D. (1968) Polarization gradient in elastic dielectrics. *Int. J. Solids. Struct.*, 4, pp. 637-642.
- Nunez-Toldra, R., Vasquez-Sancho, F., Barroca, N. and Catalan, G. (2020) Investigation of the cellular response to bone fractures: evidence for flexoelectricity. *Sci. Rep-UK.*, 10, 1, pp. 254.
- Repka, M., Sladek, V. and Sladek, J. (2018) Gradient elasticity theory enrichment of plate bending theories. *Composite Structures*, 202, pp. 447-457.
- Shu, J.Y., King, W.E. and Fleck, A.F. (1999) Finite elements for materials with strain gradient effects. *International Journal for Numerical Methods in Engineering*, 44, pp. 373-391.
- Tian, X., Sladek, J., Sladek, V., Deng, Q. and Li, Q. (2021) A collocation mixed finite element method for the analysis of flexoelectric solids. *International Journal of Solids and Structures*, 217-218, pp. 27-39.
- Tian, X., Xu, M., Zhou, H., Deng, Q., Li, Q., Sladek, J. and Sladek V. (2022) Analytical studies on Mode III fracture in flexoelectric solids. *J. Appl. Mech.*, 89, 4, pp. 041006.
- Toupin, R. A. (1962) Elastic materials with couple-stresses. *Arch. Ration. Mech. Anal.*, 11, 1, pp. 385-414.
- Vasquez-Sancho, F., Abdollahi, A., Damjanovic, D. and Catalan, G. (2018) Flexoelectricity in Bones. *Adv. Mater.*, 30, 1, pp. 1705316.
- Yudin, P., and Tagantsev, A. (2013) Fundamentals of Flexoelectricity in Solids. *Nanotechnology*, 24, 43, pp. 432001.
- Zubko, P., Catalan, G. and Tagantsev, A. K. (2013) Flexoelectric Effect in Solids. *Annu. Rev. Mater. Res.*, 43, pp. 387-421.